

# TIME 2016



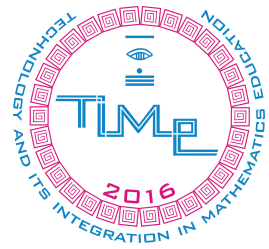
## **Study of a non linear oscillator with CAS through analytical, numerical and qualitative approaches**

**Jeanett López García**

**Jorge Javier Jiménez Zamudio**

**UNAM-México**

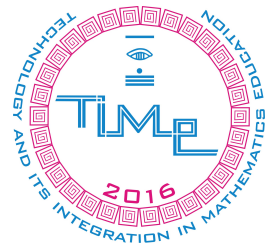
# Introduction



- ❖ According with Blanchard, Devaney and Hall (1999), Differential Equations should be taught holistically with three approaches: analytical, qualitative and numerical.
  - ❖ There are few programs in Differential Equations with these topics where non linear models appear. (In our case, for the BSc: Applied Mathematics and Computer Science).
- “The more realistic is a model in differential equations, the harder it is to find an analytical solution”**

# Introduction

---



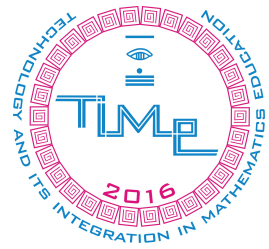
**Q1:** Where can professors find any examples more realistic, that involve the three approaches: analytic, qualitative and numerical?

Mickens (2010), in his book “**Truly nonlinear oscillators**” gave good examples of non linear oscillators, but....

**Q2:** In a first EDO course, is it possible that our students can be prepared to analyze a problem holistically with the three approaches?

**CAS could be the bridge in order to achieve it... let's see a study case!**

# Many examples of TNL



Examples of second-order, nonlinear differential equations (TNL Oscillators):

$$\ddot{x} + x^3 = 0,$$

$$\ddot{x} + x^{3/5} = 0,$$

$$\ddot{x} + x + x^{1/3} = 0,$$

$$\ddot{x} + x^2 \operatorname{sgn}(x) = 0,$$

$$\ddot{x} + (1 + \dot{x}^2)x^{1/3} = 0,$$

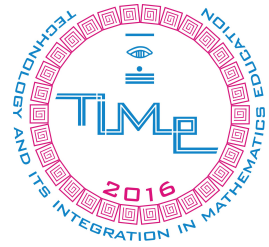
$$\ddot{x} + \frac{1}{x^{1/3}} = 0.$$



# Model



$$\frac{d^2x}{dt^2} + 4x(1+x^2)^{-\frac{3}{2}} = 0$$



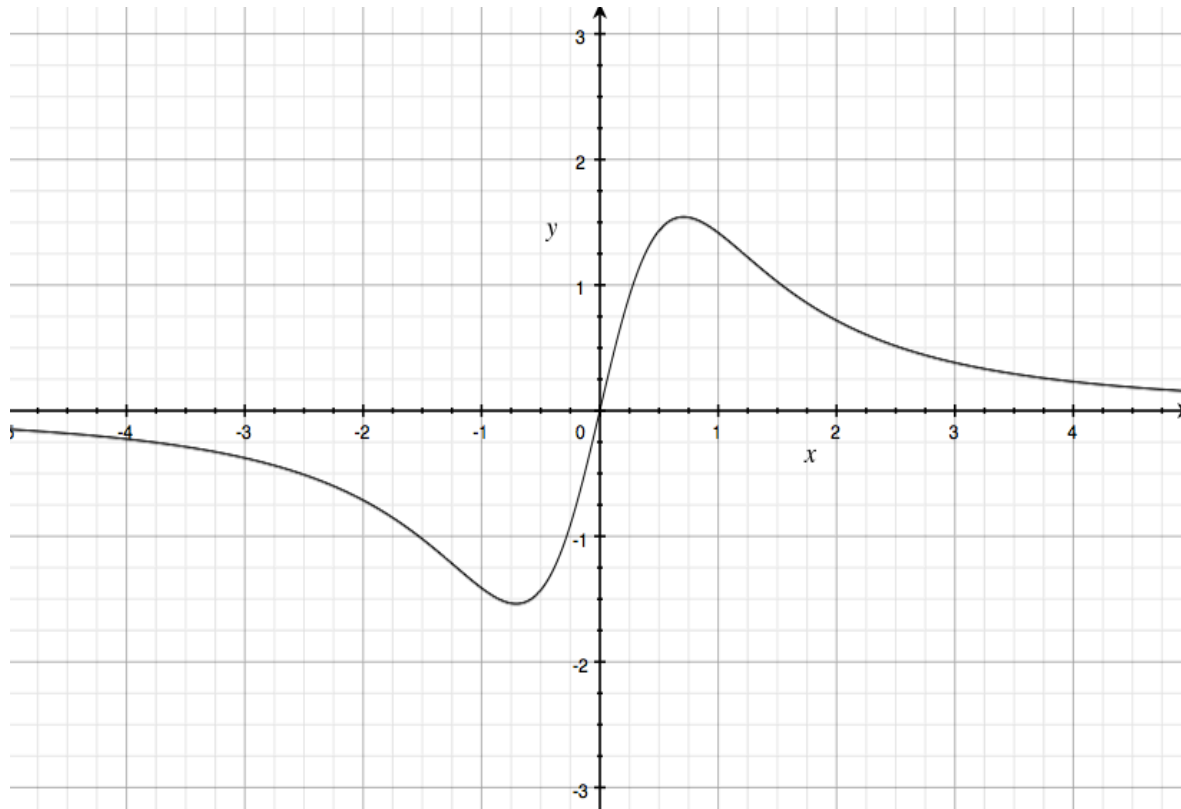
Initial condition:  $x(0) = 1, x'(0) = 0$

The nonlinear function

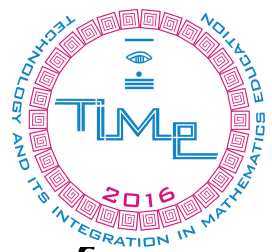
$f(x) = 4x(1+x^2)^{-\frac{3}{2}}$  is of odd parity, i.e.

$$f(-x) = -f(x)$$

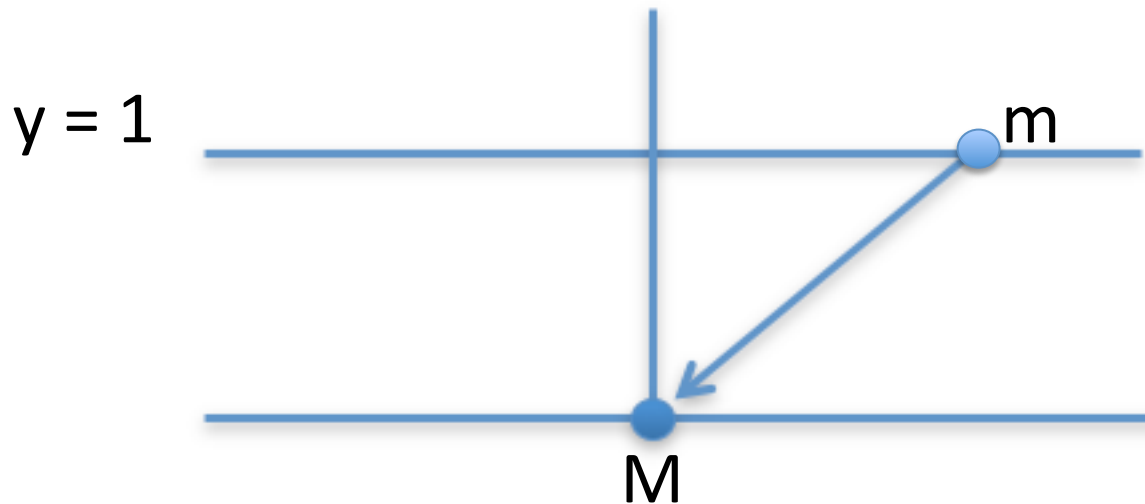
we assume that  $f(x)$   
is such that all  
solutions are  
periodic



# Model in context

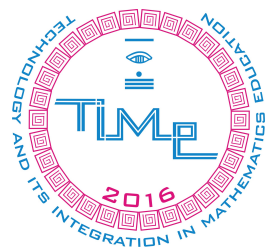


A simple interpretation would be consider a particle of mass  $m$  which is constrained to move over the line  $y = 1$



and subject to a gravitational interaction with a mass  $M$  placed at the origin.

# Model in context



The force on the particle in the x direction is given by:

$$F_x = -\frac{GmMx}{(1+x^2)^{\frac{3}{2}}} \quad F_x = -|F|\cos\theta = -\frac{GmM}{r^2}\cos\theta = -\frac{GmM}{r^2}\frac{x}{r}$$

With  $r = \sqrt{1+x^2}$       So,  $F_x = -\frac{GmMx}{(1+x^2)^{\frac{3}{2}}}$

Newton's second law provides us the equation of motion, described as:

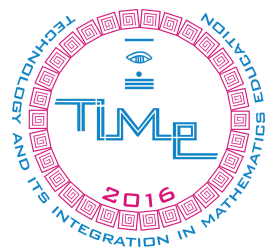
$$ma = F_x = -\frac{GmMx}{(1+x^2)^{\frac{3}{2}}} = m\ddot{x}$$

Let constants:  $GM=4$

Therefore,  $\frac{d^2x}{dt^2} + 4x(1+x^2)^{-\frac{3}{2}} = 0$

# Looking for a solution

---



Three methods exist for carrying out this task:

- (1) the use of **analytical methods** in order to find first-integrals,
- (2) the use of **qualitative methods** based on examining the geometrical properties of the trajectories in the 2-dim phase-space, and
- (3) the use **numerical analysis**

# Looking for a solution

"the easy way, without understanding"

It is very common for students tempted to implement immediately the differential equation with some software, using Wolfram alpha or Grapher

## WOLFRAM ALPHA (online)

WolframAlpha computational knowledge engine

Input:  $y'' + 4y(1+y^2)^{-3/2} = 0$

Autonomous equation:

$$y''(x) = -\frac{4y(x)}{(1+y(x)^2)^{3/2}}$$

ODE classification: second-order nonlinear ordinary differential equation

Alternate forms:

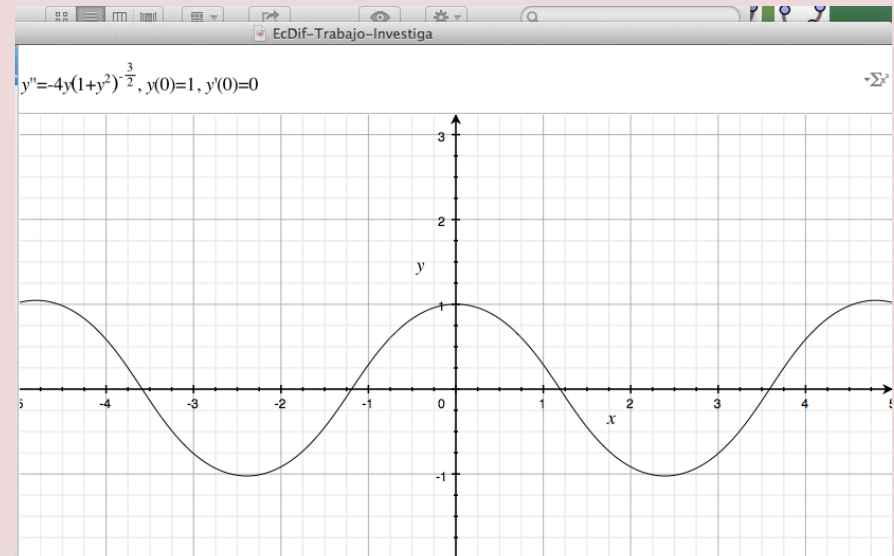
$$(y(x)^2 + 1)^{3/2} y''(x) = -4y(x)$$

$$\frac{(y(x)^2 + 1)^{3/2} y''(x) + 4y(x)}{(y(x)^2 + 1)^{3/2}} = 0$$

Plots of sample individual solutions:

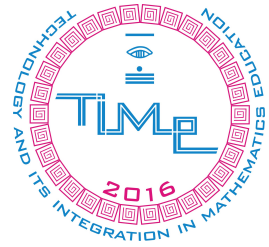
- $y(0) = 1, y'(0) = 0$
- $y(0) = 0, y'(0) = 1$

## GRAPHER (McIntosh)



# Analytical method

## First-Integrals



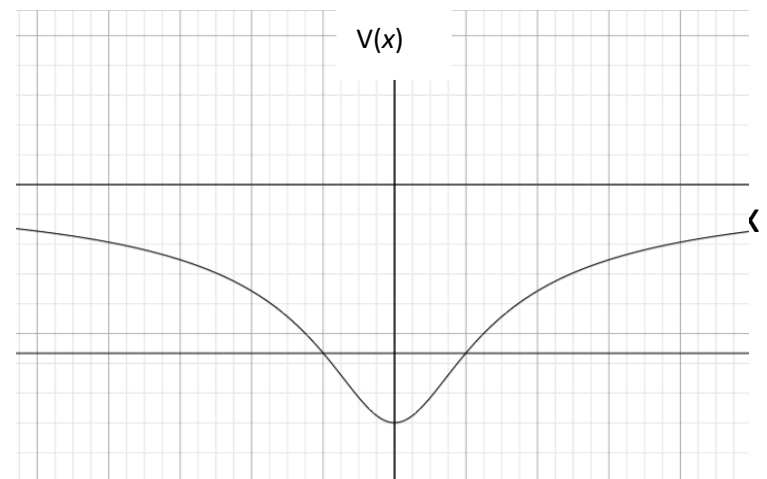
As  $f(x) = 4x(1+x^2)^{-\frac{3}{2}} \neq \begin{cases} f(t) \\ f(\dot{x}) \end{cases}$ , it can be shown that energy is conserved.

So, the potential energy is calculated:

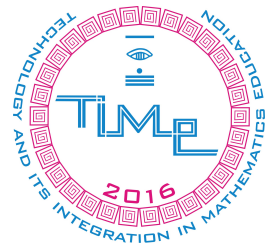
$$V(x) = - \int f(x) dx = \int \frac{4x}{(1+x^2)^{\frac{3}{2}}} dx$$

Let  $u = (1+x^2)$ ;  $du = 2x dx$

$$V(x) = \int 2u^{-\frac{3}{2}} du = 2u^{-\frac{1}{2}} (-2) = -\frac{4}{(1+x^2)^{\frac{1}{2}}}$$



# Analytical method



Reduction of order 2 to 1  $\rightarrow$  Find out a first-integral of the equation

This is done by multiplying  $\dot{x} = \frac{dx}{dt}$

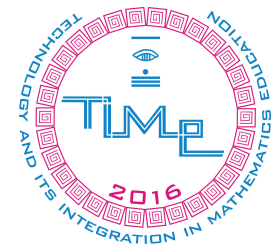
Substituting have:  $\frac{d}{dt} \left( \frac{1}{2} \dot{x}^2 \right) = f(x) \frac{dx}{dt} = - \frac{dV}{dx} \frac{dx}{dt} = - \frac{dV}{dt}$

$$\frac{d}{dt} \left( \frac{1}{2} \dot{x}^2 + V \right) = 0$$

Therefore,  $\left( \frac{1}{2} \dot{x}^2 - \frac{4}{(1+x^2)^{\frac{1}{2}}} \right) = E = -2\sqrt{2}$

where the initial conditions were used to evaluate E.

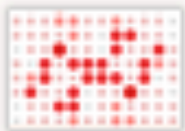
# Analytical method



So, the 1st-order ODE resulting is:  $\frac{1}{2}\dot{x}^2 = \frac{4}{(1+x^2)^{\frac{1}{2}}} - 2\sqrt{2}$

$$\frac{dx}{dt} = \sqrt{\frac{8}{(1+x^2)^{\frac{1}{2}}} - 4\sqrt{2}}$$

Again, with Wolfram Alpha....



**Standard computation time exceeded...**



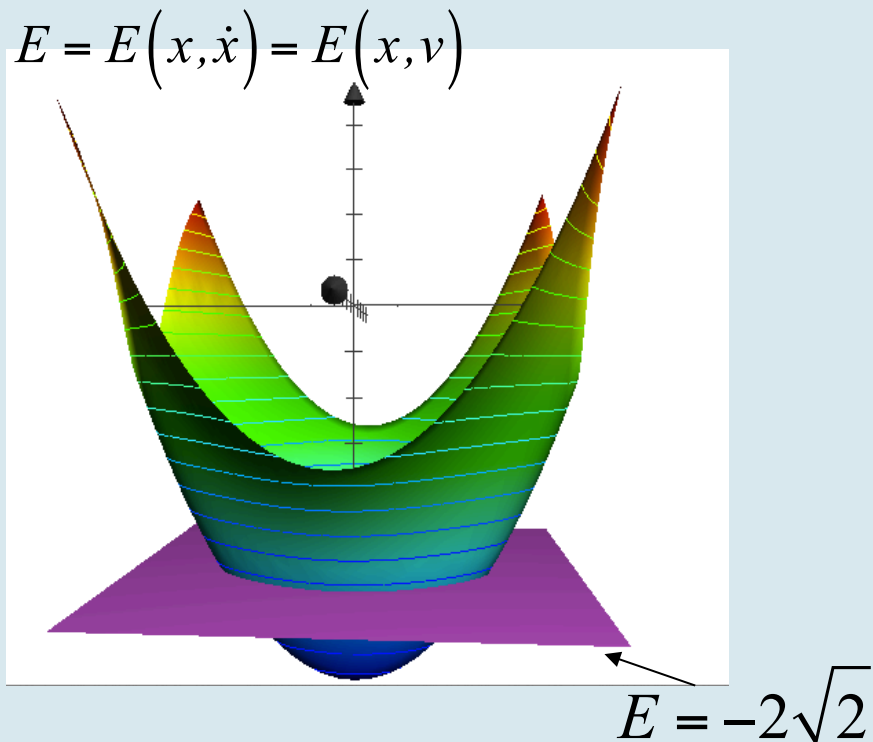
**Divergent  
algorithm!**



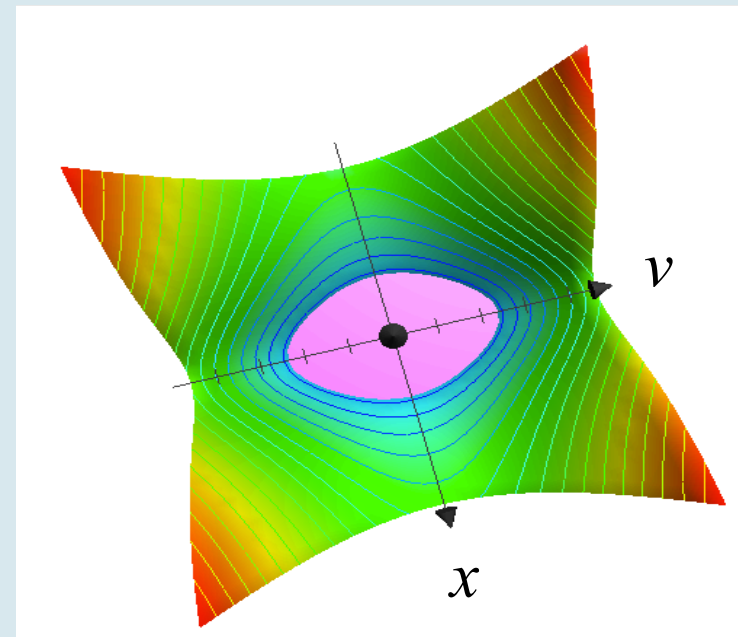
# Connection with qualitative method

It can be seen that the energy drawn, it represents a closed curve (contour) in the projection in the plane  $x$  vs.  $v=dx/dt$

Potential function and the plane representing the constant energy  $E = -2\sqrt{2}$



Projection in the plane, with contour lines for different values of energy



Phase plane

# Qualitative method

The second-order differential equation, may be reformulated to two first-order system equations

$$\dot{v} = f(x), \quad \dot{x} = v$$

i.e.

$$\dot{x} = v$$

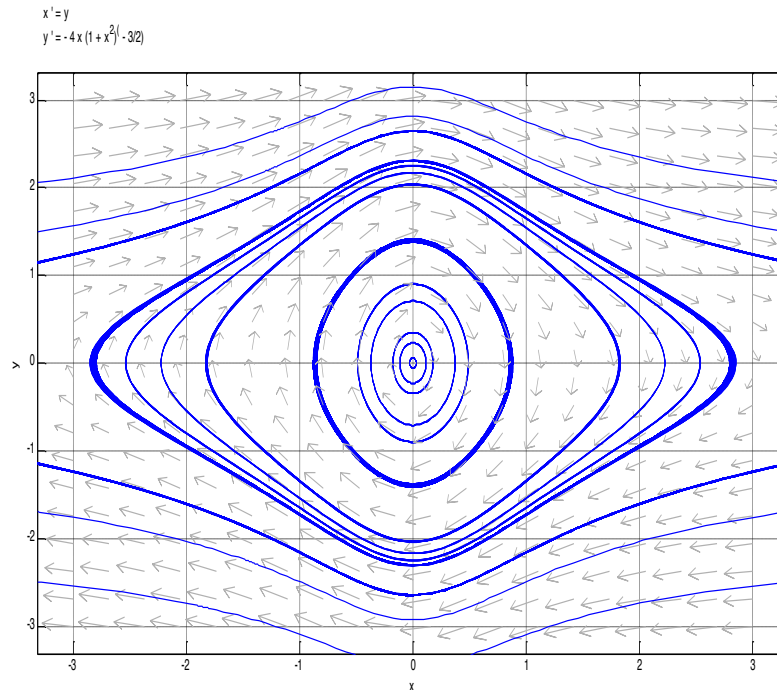
$$\dot{v} = 4x \left(1 + x^2\right)^{-\frac{3}{2}}$$

As usual, the  $x$  is interpreted as the position of the particle and the speed  $v$ , both dependent functions of time  $t$ .

The variables  $x$  and  $v$  define a 2-dim phase-space which we denote as  $(x, v)$  proposed by H. Poincaré.

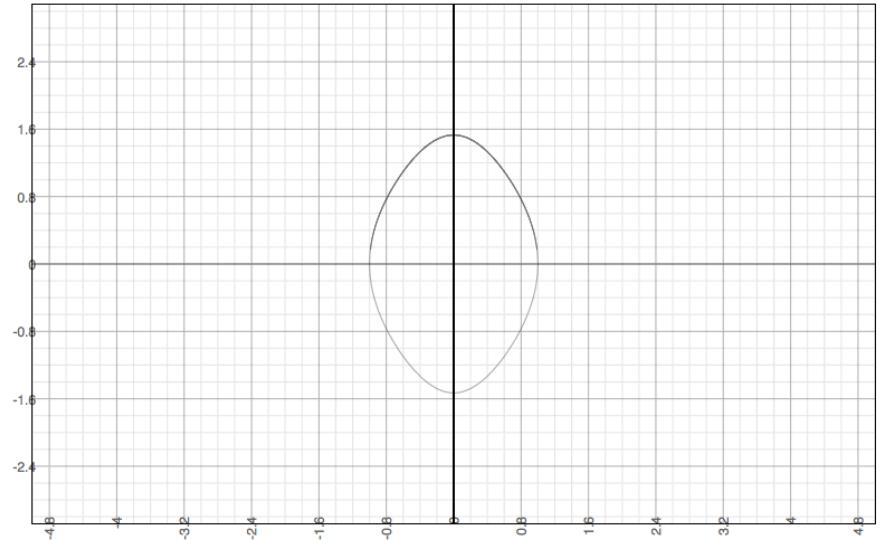
# PPLANE - MATLAB

Some of the curves drawn on the **vector field** represent particular solutions when the trajectory associated with the initial values in the phase plane is followed, sometimes called the phase portrait.

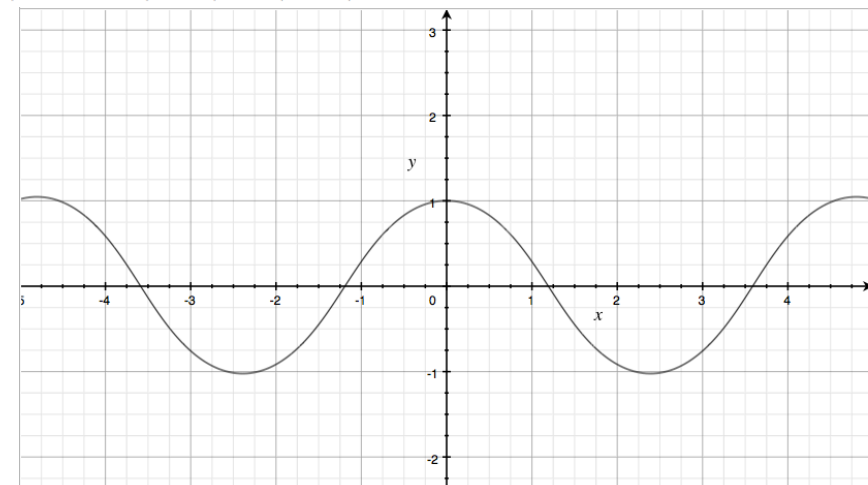


# Closed Phase-Space Trajectories

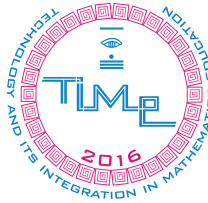
In particular, for  $(x_0, v_0) = (1, 0)$



In this qualitative approach:  
it was easy, students can  
recognized that closed curves in  
phase-space correspond to  
periodic solution.



# Numerical method



ODE System first order  Application of **Euler algorithm?**

$$x_{n+1} = x_n + v_n h$$

$$v_{n+1} = v_n + F_n h$$

$$t_n = t_0 + nh$$

**Disadvantages:** It is unstable and not preserve energy.

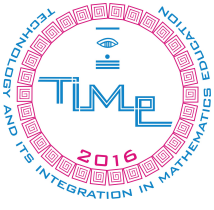
**Vs. Euler-Cromer algorithm**

$$x_{n+1} = x_n + v_{n+1} h$$

$$v_{n+1} = v_n + F_n h$$

**Advantages:** It produces stable oscillation, and preserves the total energy produced in each cycle of oscillation.

# Euler-Cromer algorithm implemented in Maple



Maple code:

## Section 1: Enter data

```
>f:=(t,x)->-4*x(t)*(1+x(t)*x(t))^(3/2);
```

$$f:=(t,x) \rightarrow -\frac{4x(t)}{(1+x(t)x(t))^{3/2}}$$

Initial conditions

```
>t0:=0.0:
```

```
>x0:=1.0:
```

```
>v0:=0.0:
```

```
>tf:=4.65:
```

```
>ics := x(0)=1.0, D(x)(0)=0.0:
```

## Section 2: Approach solution

Step 1

```
>h:=(tf-t0)/20.0;
```

$$h := 0.2325000000$$

```
>X[0]:=x0;
```

```
V[0]:=v0;
```

$$X_0 := 1.0$$

$$V_0 := 0.$$

```
>f(t0,X[0]);
```

```
V[1]:=V[0]+f(t0,X[0])*h;X[1]:=X[0]+V[1]*h;
```

$$-1.414213564$$

$$V_1 := -0.3288046536$$

$$X_1 := 0.9235529180$$

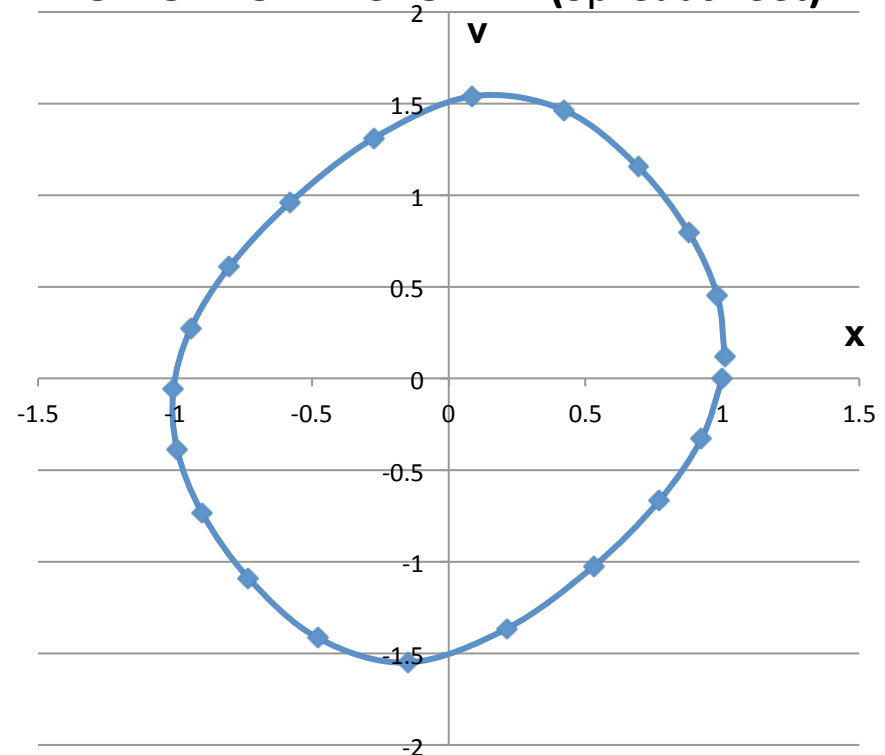
Total iterations: 20

# Results: Euler-Cromer algorithm

The result for  $n = 20$  iterations shown in the following table with the calculation of energy at each step

n	Xn	Vn	En	$\Delta(E)$
0	1	0	-2.82842712	
1	0.92355292	-0.32880465	-2.88446031	-0.05603318
2	0.76793374	-0.6693298	-2.94848228	-0.06402197
3	0.52947309	-1.02563719	-3.00909619	-0.06061391
4	0.2119881	-1.36552687	-2.98071039	0.0283858
5	-0.14840912	-1.55009556	-2.7552659	0.22544449

**NUMERICAL PHASE CURVE ASSOCIATED WITH THE METHOD OF EULER-CROMER (Spreadsheet)**



6	-0.42111111	-1.66666667	-2.66666667	0.08333333
7	-0.70710678	-1.73205081	-2.60975000	0.05635000
8	-0.95105652	-1.73205081	-2.50000000	0.03333333
9	-1.11803399	-1.66666667	-2.35355339	0.01444661
10	-1.20710678	-1.55009556	-2.17526590	0.00844449
11	-1.20710678	-1.41421356	-2.07071039	0.00533333
12	-1.11803399	-1.26491106	-2.00000000	0.00333333
13	-0.95105652	-1.11803399	-1.95710678	0.00222222
14	-0.70710678	-0.95105652	-1.94071039	0.00144444
15	-0.42111111	-0.70710678	-1.95000000	0.00083333
16	-0.14840912	-0.42111111	-1.98446031	0.00044449
17	0.69177505	1.15383861	-2.62391681	-0.00840372
18	0.87684401	0.79599553	-2.69075226	-0.06683545
19	0.98132137	0.44936502	-2.75400039	-0.06324813
20	1.00864811	0.11753434	-2.80931624	-0.05531585

**Students can check is the same closed curve!**

# Conclusions / Reflections

---



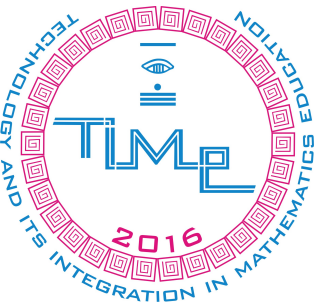
- ❖ Our purpose is linking research-teaching with cutting edge topics, as non linear differential equations.
- ❖ The qualitative technique is more powerful since it may be applied in all situations, in comparison with the analytical technique.
- ❖ The goal is to show that either all or some of the trajectories in the phase-plane are closed. Since closed trajectories correspond to periodic solutions, the existence of periodic solutions was established.



# Conclusions / Reflections



- ❖ Visualization helps intuitive understanding.
- ❖ The learning-teaching process is shorter and dynamic in order to visualize that the vector field, potential function, phase plane, etc., associated with the differential equations.
- ❖ A good combination of CAS could give us the three analysis. Such as: Maple, MatLab, Graph, and Excel.
- ❖ We say that how much software that we have to use depends on the dynamics of the class.



# TIME 2016



TIME

---

**Thank you!**

**¡Gracias!**

---